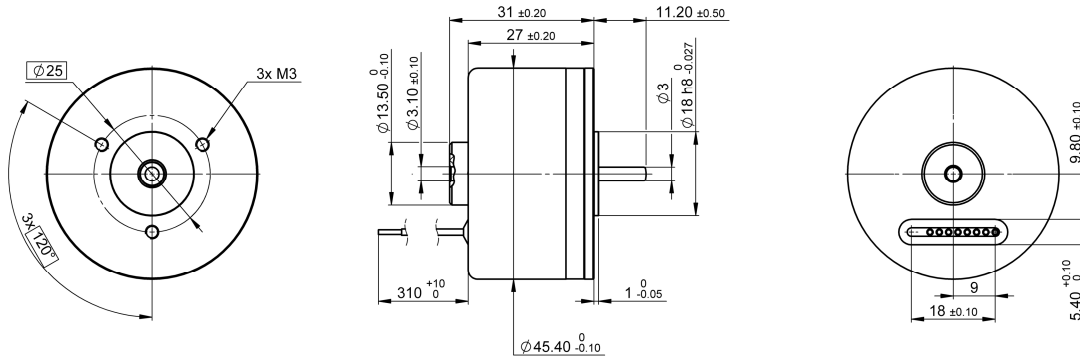


**BRUSHLESS MOTOR – HALL SENSORS OR SENSORLESS**



**Motor parameters (25°C)**

		1	2
Phase-Phase resistance	ohm	0.034	0.134
Torque constant	mNm/A	2.15	4.30
Back EMF constant	V/Krpm	0.23	0.45
Phase-Phase inductance	mH	0.021	0.08
Motor constant	mNm/vW	11.7	11.7
Rotor inertia	10 <sup>-7</sup> Kg.m <sup>2</sup>	3.0	3.0
Mechanical time constant	ms	2.2	2.2
Electrical time constant	ms	0.63	0.63

**Dynamic parameters at nominal voltage (25°C)**

		1	2	
<b>No load</b>	Nominal voltage	V	12	24
	Current	mA	960	480
	Speed	rpm	53'100	53'100
	Electrical input power	W	11.5	11.5
<b>Peak efficiency</b>	Current	A	16.0	8.0
	Torque	mNm	32.9	32.9
	Speed	rpm	50'900	50'900
	Electrical input power	W	192	192
	Mechanical output power	W	201175	176
Efficiency	%	91%	91%	

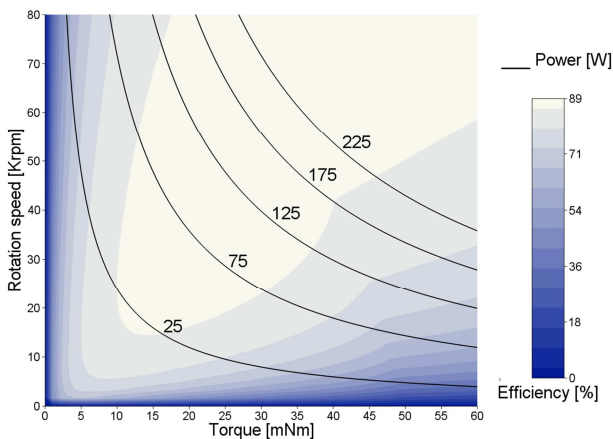
**Motor specifications**

Number of pole pairs	-	1
Number of phases	-	3
Motor Mass	g	140
Thermal resistance	°C/W	12
Max permissible winding temperature	°C	155

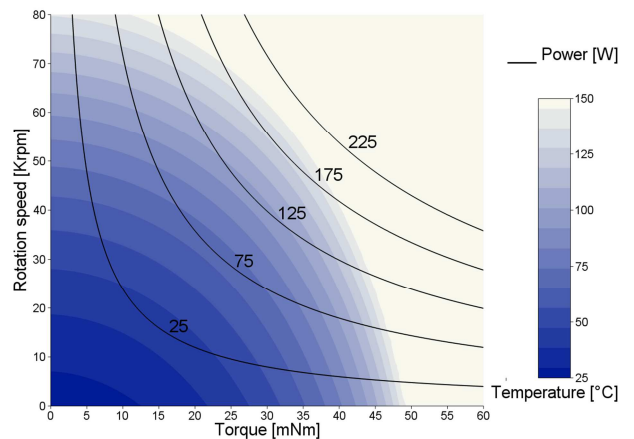
**Motor configurations**

All Electromag motors are available with custom configurations. Mechanical interface, windings and motor characteristics can be customized for each application. This generic outline drawing only shows the envelope of the motor. For detail dimensions and tolerances, please contact the factory.

**Efficiency & Mechanical power**



**Temperature & Mechanical power**



**Notes**

Efficiency and temperature maps are obtained using a heat sink that reduces the motor thermal resistance by 50% (typical case). Continuous operation is allowed until the maximum winding temperature has been reached. Beyond this point, intermittent operation or additional cooling should be considered.

Rev 2014.08. Specifications are subject to change without prior notice