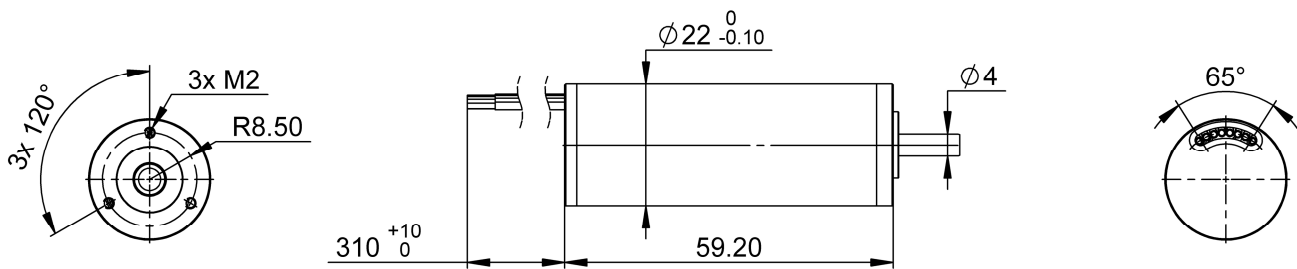


**BRUSHLESS MOTOR – HALL SENSORS OR SENSORLESS**

**Motor parameters (25°C)**

		1	2
Phase-Phase resistance	ohm	0.182	0.425
Torque constant	mNm/A	4.49	6.68
Back EMF constant	V/Krpm	0.470	0.700
Phase-Phase inductance	mH	0.03	0.08
Motor constant	mNm/vW	10.5	10.2
Rotor inertia	10 <sup>-7</sup> Kg.m <sup>2</sup>	4.2	4.2
Mechanical time constant	ms	3.8	4.0
Electrical time constant	ms	0.15	0.19

**Dynamic parameters at nominal voltage (25°C)**

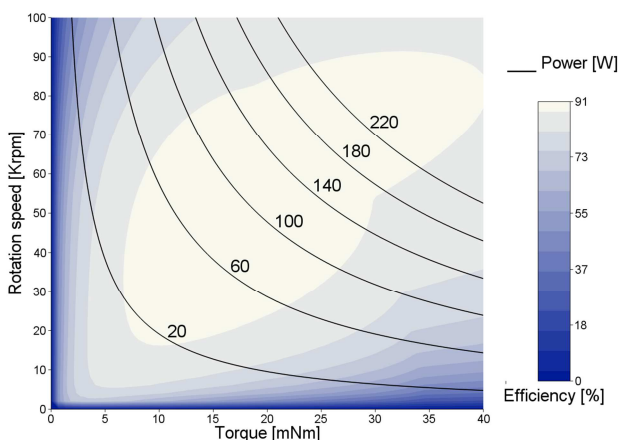
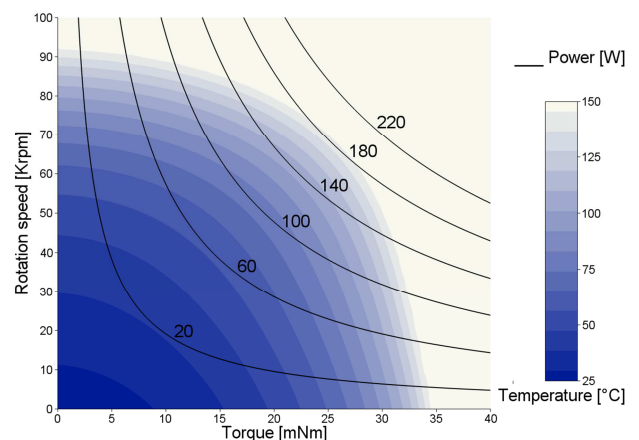
		1	2	
<b>No load</b>	Nominal voltage	V	24	24
	Current	mA	250	130
	Speed	rpm	51'000	34'200
	Electrical input power	W	6.0	3.1
<b>Peak efficiency</b>	Current	A	4.7	2.2
	Torque	mNm	19.9	13.9
	Speed	rpm	48'300	32'300
	Electrical input power	W	112.5	53.1
	Mechanical output power	W	100.8	47.0
Efficiency	%	90%	89%	

**Motor specifications**

Number of pole pairs	-	1
Number of phases	-	3
Motor Mass	g	139
Thermal resistance	°C/W	12
Max permissible winding temperature	°C	155

**Motor configurations**

All Electromag motors are available with custom configurations. Mechanical interface, windings and motor characteristics can be customized for each application. This generic outline drawing only shows the envelope of the motor. For detail dimensions and tolerances, please contact the factory.

**Temperature & Mechanical power (motor 2)**

**Temperature & Mechanical power (motor 2)**

**Notes**

Efficiency and temperature maps are obtained using a heat sink that reduces the motor thermal resistance by 50% (typical case). Continuous operation is allowed until the maximum winding temperature has been reached. Beyond this point, intermittent operation or additional cooling should be considered.

Rev 2014.08. Specifications are subject to change without prior notice